PROJECT: SRMS
ASS'T MOMERCEATURE: ROYATIONAL HAND CONTROLLER

SYSTEM: DAC SUBSYSTEM

HEET:

PMEA REF.	REV.	MANE OTY & DRAWING REF. DESIGNATION	FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	HOUR / FUNC. I/I CRITICALITY RATIONALE FOR ACCEPTANCE
	2	ROTATIONAL HAND CONTROLLER QTY-1 SPAR P/M S115SE117	HODE: UNCOMMANDED OUTPUT IN ANY ONE AXIS. CAUSE(S): (1) RHC DEMODULATOR TRANSISTOR COLLECTOR FAILS OPEN. (2) RHC DEMODULATOR TRANSISTOR B-E JUNCTION FAILS SHORTED. (3) RETURN SPRING FRACTURES.	CAUSE (1) ONE AXIS MAS PERHAHENT RATE COMMAND OF 2/3 OF MAX. ARM MAY TAKE UNEXPECTED TRAJECTORY. CAUSE (2) SAMC AS ABOVE RATE COMMAND OF F/3 OF MAX. CAUSE (3) ONE AXIS HAS PERHAMENT RATE COMMAND AT LAST POSITION ARM MAY TAKE UMEXPECTED TRAJECTORY. WORST CASE UNEXPECTED TRUMMANA, UNEXPORTED CREM ACTION REQ. REDUNDANT PATHS REMAINING N/A	THREE IDENTICAL CIRCUITS PROVIDE SIGNAL DEMODULATION FOR EACH OF THE THREE TRANSDUCERS. IM EACH CIRCUIT, THO TRANSISTORS ARE ALTERNATELY SWITCHED BY THE THREE STANSDUCERS. IM EACH CIRCUIT, THO TRANSISTORS ARE ALTERNATELY SWITCHED BY THE THREE STORES RESULTS IN PHASE-SENSITIVE RECTIFICATION OF THE TRANSDUCER OUTPUT. THE RECTIFIED OUTPUT 1S FILTERED AND SCALED BY AN OPERATIONAL APPLIFIER. ONE TRANSFORMER PROVIDES THE SWITCHING COMMANDS FOR ALL THREE CIRCUITS. TRANSISTORS ARE 2M2432A TYPE. OP ARPS ARE TYPE UNIDED. EEE PARTS HAVE BEEN SELECTED AND CONTROLLED IN ACCORDANCE WITH SPAR-RRS-PA.003. THIS DOCUMENT DEFINES THE PROGRAM REQUIRER HIS FOR MONITORING AND CONTROLLED IN ACCORDANCE WITH SPAR-RRS-PA.003. THIS DOCUMENT DEFINES THE PROGRAM REQUIRER HIS FOR MONITORING AND CONTROLLED IN ACCORDANCE WITH EQUIPMENTS FOR MONITORING AND CONTROLLED IN ACCORDANCE WITH REQUIRER HIS FOR MONITORING AND CONTROLLED IN ACCORDANCE WITH REQUIRER HIS FOR MONITORING AND CONTROLLED IN ACCORDANCE WITH REQUIRER HIS FOR MONITORING AND CONTROLLED IN ACCORDANCE WITH REQUIRER HIS FOR MONITORING AND CONTROLLED TO THE STRESS LEVELS. PROCEDURES AND ACQUARE CERTIFIED TO ENSURE AT LEAST EQUIVALENT QUENTLY FOR MONITORING AND TRACELLAR HIS FOR MONITORING AND STRUCTURAL/MECHANICAL/INTEGRITY OF ASSEMBLIES ARE APPLIED. SIGNAL SHAPE AND ASSEMBLY CHECKLISTS. MAREFALL SELECTION AND USAGE CONFORMS TO SPAR-SC. 168 WHICH IS EQUIVALENT TO THE MASA MATERIALS USAGE REQUIREMENTS. MONITORING SELECTION AND USAGE CONFORMS TO SPAR-SC. 168 WHICH IS EQUIVALENT TO THE MASA MATERIALS USAGE REQUIREMENTS. MONITORING SELECTION AND THE MASA MATERIALS SHAPE AND COMPONENT TO THE MASA MATERIALS USAGE REQUIREMENTS. MONITORING SELECTION AND USAGE CONFORMS TO SPAR-SC. 168 WHICH IS EQUIVALENT TO THE MASA MATERIALS USAGE REQUIREMENTS. MONITORING SELECTION AND USAGE CONFORMS TO SPAR-SC. 168 WHICH IS EQUIVALENT TO THE MASA MATERIALS SHAPE AND COMPONENT HAS SEEN COMPONENT HAD SECOND FOR EDUTION FO

PREPARED BY: NYMC

SUPERCEDING DATE: 06 OCT BY

APPROVED BY

DATE:

CRITICAL ITEMS LIST

PROJECT: SRMS

ASS'Y MONERCLATURE: HOYAYIONAL HAND CONTROLLER

ASS'Y P/A: 51155E117 SHEET:

THEA REF.	REV.	NAME OTY & DRAWING REF. DESIGNATION	FAILURE HODE AND CAUSE	FAILURE EFFECT ON END ITEN	HDWA / FUNC. 1/1 CRETICALITY	RATIONALE FOR ACCEPTANCE	
1460	2	ROTATIONAL HANG CONTROLLER GTY-I SPAR P/M SIISSEII7	MODE: UNCOMMANDED OUTPUT IN ANT ONE AXIS. CAUSE(S): (1) RHC DENOCULATOR TRANSISTOR COLLECTOR FAILS OPEN. (2) RHC DENOCULATOR TRANSISTOR B-E JUNCTION FAILS SHORTED. (3) RETURN SPRING FRACTURES.	CAUSE (1) ONE ALIS HAS PERMAMENT RATE COMMAND OF 2/3 OF HAX. ARM MAY TAKE UNEXPECTED TRAJECTORY. CAUSE (2) SAHE AS ABOVE RATE COMMAND OF 1/3 OF HAY. CAUSE (3) ONE AXIS HAS PERMAMENT RATE COMMAND AT LAST POSITION AND HAY TAKE UNEXPECTED TRAJECTORY. WORST CASE UNEXPECTED MOTION. 6 JOINT RUMANAY. UNANHUNCLATED. CREW ACTION REQ. REDUNDANT PATHS RENALMING			1

REPARED BY: MFMG	SUPERCEDING DATE: 06 OCT 87	APPROVED BY:	DATE:

PREPARED BY: WHG

PROJECT: SRMS
ASS'Y MONERCLATURE: ROTATIONAL HAND CONTROLLER

STSTEM: DEC SUBSYSTEM. ASS'Y P/N: SIISSEIIT

~ SHEET: _____]

REF. REV.	DANING REF. DESIGNATION	FAILURE MODE AND CAUSE	FAILURE EFFECT ON END LIEN	HOUR / FUNC. 1/1 RATIONALE FOR ACCEPTANCE CRITICALITY
1460 2	ROTATIONAL HAMD CONTROLLER QTP SPAR P/M 51155E117	MODE: UNCOMPANDED: OUTPUT IN ANY ONE AXIS. CAUSE(\$): (I) RHC DEMODULATOR TRANSISTOR COLLECTOR FAILS OPEN. (2) RHC DEMODULATOR TRANSISTOR B-E JUNCTION FAILS SHORTED. (3) RETURN SPRING FRACTURES.	CAUSE (1) ONC AXIS HAS PERHAMENT RATE CONHAND OF 2/1 OF MAK. ARM HAY TAKE UMEXPECTED TRAJECTORY. CAUSE (2) SAME AS ABOVE RATE COMMAND OF 1/3 OF MAX. CAUSE (3) ONE AXIS HAS PERHAMENT RATE COMMAND AT LAST POSITION. ARM HAY TAKE UNEXPECTED TRAJECTORY. WORST CASE UNEXPECTED HOTIOM. 6 JOINT RUMAMAY. UMANMUNCIATED. CREW ACTION REQ. REDUNDANT PATHS REMAINING M/A	THE RICC IS SUBJECTED TO THE FOLLOWING ACCEPTANCE ENVIRONMENTAL TESTING AS AN SRU. O VIDRATION: LEVEL AND DURATION REFERENCE TABLE I O THERMAL: *120 DEGREES F TO 20 DEGREES F (12 MRS PER CYCLES TOTAL. THE RICC IS TESTED AS PART OF THE DEC SUBSYSTEM; MINICH CONSIST OF DEC PAREL, THE AND RIC; PER TP 247. THE FOTAL DEC SUBSYSTEM UNDERGOUS RMS SYSTEM TESTING, (TP SIB RMS STRONGBACK, AND TP552 FLAT FLOOR TESTS) WHICH VERIFIES THE ABSENCE OF THE FAILURE MODE. QUALIFICATIONS TESTS THE RICC IS CERTIFIED BY SIMILARITY TO THE ORBITTEM USED RICC EXCEPT FOR FINGER OPERATED SWITCHES. THE BASIC DIFFERENCES IS THAT THE ORBITTEM RIC IS TRIPLE REDUNDANT AND THE RIS RICC IS SYNCLE STRING. FLIGHT CHECKOUT PORS OPS CHECKLIST (ALL VEHICLES) JSC 16987

FMEA NCF.	REV. DRI	HE OTY & PAUING REF. SIGNATION	FAILURE MODE AND CAUSE	FAILUME EFFECT ON END ITEM	HOWN / FUNC. I/I RATIONALE FOR ACCEPTANCE CRITICALITY
1460	HAI COI QT' SPI	TATIONAL IND	MODE: UNCOMMANDED OUTPUT IN ANY ONE AXIS. (1) RHC DEMODULATOR TRANSISTOR COLLECTOR FAILS OPEN. (2) RHC DEMODURATOR TRANSISTOR D-E JUNCTION FAILS SHORTED. (3) RETURN SPRING FRACTURES.	CAUSE (1) OME AXIS HAS PERMANENT MATE COMMAND OF 2/3 OF HAX. ARM MAY TAKE MICKPECTED TRAJECTORY. CAUSE (2) SAME AS ABOVE RATE COMMAND OF 1/3 OF HAX. CAUSE (3) OME AXIS HAS PERMANENT RATE COMMAND AT LAST POSITION ARM MAY TAKE UMEXPECTED TRAJECTORY. MORST CASE UMEXPELLED MOTHOM. & JOINT MUMANNUNCIATED CREM ACTION REDUNDANT PATHS REMAINING M/A	ETE PARTS INSPECTION IS PERFORMED AS REQUIRED BY SPAR-AMS-PA. 003. EACH ETE PART IS QUALIFIED AT THE PART LEVEL TO THE REQUIREMENS OF THE APPLICABLE SPECIFICATION. ALL ETE PARTS ARE 100K SCREENED AND BURNED IN AS A RINKERM. AS REQUIRED BY SPAR-AMS-PA. 003. BY THE SUPPLIER. ADDITIONALLY. ETE PARTS ARE 100K SCREENED IN ACCORDANCE WITH REQUIREMENTS. BY AN INDEPENDENT SPAR APPROVED TESTING FACILITY. 0PG 18 PERFORMED AS REQUIRED BY PA. 003 ON A RANDOWLY STLECTED SK OF PARTS. MAXIMUM S PIECES, MINIMUM J PIECES FOR LIFE IS PROCURED TO SPECIFICATION HIL-W-22759 OR MIL-W-81301 AND INSPECTED AND TISTED TO MASA JSCHOOLOG STANDARD NUMBER "96. RECEIVING INSPECTION VERIFIES THAT ALL PARTS RECEIVED ARE AS IDENTIFIED IN THE PROCUBERRY DOCUMENTS, THAT MO PHYSICAL DAMAGE TO PARTS HAS OCCURRED DURING SHIPMENT AND THAT APPROPRIATE DATA HAS BEEN RECEIVED WHICH PROVIDES ADEQUATE TRACEABILITY INFORMATION AND IDENTIFIES ACCEPTABLE PARTS. THE TRANSDUCER ASSY COMSISTING OF A TRANSDUCER, DAY LUBE BEARINGS AND SPRINGS ETC. ARE BOUGHT OUT PARTS AS REQUIRED BY CAL SPEC PESTIPME. HASPECTIONS ARE PERFORMED BY THE SUPPLIER CLIFTON PRECISION TO VERIFY THAT EACH MANUFACTURING, ASSEMBLY AND IEST OPERATION IS SATISAFCTORILLY COMPLETED. PARTS ARE INSPECTED THROUGHOUT HANDFACTURING, ASSEMBLY AND IEST OPERATION IS SATISAFCTORILLY COMPLETED. TRESE COMPONENT MOUNTING INSPECTION FOR CORRECT SOLDERING, MIRE LOOPING STRAPPING, ETC. OPERATORS AND INSPECTION, DAMAGE AND ADEQUACY OF PLATED THROUGH HOLES. COMPONENT MOUNTING INSPECTION FOR ADEQUATE PROCESSING IS PERFORMED USING QUIRAVIOLET LIGHT TECHNIQUES. COMPONENT MOUNTING, STRAPPING OF MATCH PROCESSING IS PERFORMED USING QUIRAVIOLET LIGHT TECHNIQUES. COMPONENT MOUNTING, STRAPPING OF MIRE ETC. PRE-CLOSURE INSPECTION, MORKMANSHIP A CLEAM INESS (HONEYMELL/GOVERNMENT REP HANDATORY INSPECTION PRICALOURE INSPECTION, MORKMANSHIP AND CLEAM INSPECTION CONTACT MATING, MIRE MOUTHOR, STRAPPING OF MIRE ETC. PRE-COCUPTION ON S DESIGNED OF MARCH AND THE MERCET BOARD PRICALOUR HIRE TO BE SELECTED. PRE-COCUPTI

PREPARED BY: WMG SUPERCEDING DATE: 04 OCT 07 APPROVED BY: DATE:

FMEA REF. REV.	DESIGNATION	FAILURE HODE AND CAUSE	FAILUME EFFECT ON END ITEM	HOMR / FUNC. 1/6 RAFIONALE FOR ACCEPTANCE CRITICALITY
1460 2	ROTATIONAL HAND CONTROLLER GIT-I SPAR P/M S115SE117	MODE: UNCOMMANDED OUTPUT IN ANY ONE ARIS. CAUSE(S): (I) RHC DERODULATOR TRANSISTOR COLLECTOR FAILS OPEN. (2) RHC DERODULATOR TRANSISTOR B-E JUNCTION FAILS SHORTED. (J) RETURN SPRING FRACTURES.	CAUSE (1) OHE AXIS HAS PERMANENT RATE COMMAND OF 2/3 OF MAX, ARM HAY TAKE UREXPECTED TRAJECTORY. CAUSE (2) SANCA AS ABOVE MATE COMMAND OF 1/3 OF MAX. CAUSE (3) OME AKIS HAS PERMANENT MATE COMMAND AT LAST POSITION ARM HAY TAKE UNEXPECTED TRAJECTORY. WORST CASE UNEXPECTED HOTION & JOINT RUMANAT. UMANHUNCIATED. CREW ACTION REG. REDUMDANT PATHS REMAINENG	A TEST READINCSS REVIEW (TRN) WHICH INCLUDES VERIFICATION OF TEST PERSONNEL TEST DOCUMENTS, TEST EQUIPMENT CALIBRATION/VALIDATION STATUS AND HARDWARE CONFIGURATION IS CONVEND BY QUALITY ASSUMANCE IN COMJUNCTION WITH ENEMPERATING RELIABILITY, CONFIGURATION CONTROL SUPPLIER AS APPLICABLE AND THE GOVERNMENT REPRESENTATIVE, PRIOR TO THE START OF ANY FORMAL TESTING (ACCEPTANCE OR QUALIFICATION). ACCEPTANCE TESTING (AIP) INCLUDES, ANDIEMT, VIBRATION AND THERMAL TESTING (CAE/GOVERNMENT REP MANDATORY INSPECTION FOINT) INTECRATION OF DEC PANEL, RINC, THE AND REID INSPECTIONS ARE PERFORMED AT EACH STACE OF INTECRATION, WHICH INCLUDES GROUNDING CHECKS, INTER COMMECT CABLE VERIFICATION, CONNECTOR INSPECTION FOR BENT ON PUSHBACK CONTACTS EYC. SUB-SYSTEM PERFORMANCE TESTING (ATP), PANCLUDES AN ARBIENT PERFORMANCE TEST, (MANDATORY INSPECTION OF MECHANICAL ARM SUBASSEMBLIES AND THE FLIGHT CABIN EQUIPMENT TO FORM THE SRMS. PROSPECTIONS ARE PERFORMED AT EACH PANSE OF INTEGRATION MICH INCLUDES GROUNDING CHECKS, THRU WIRING CHECKS, WIRING ROUTING, INTERFACE CONNECTORS FOR BENT ON PUSH BACK CONTACTS ETC. SAMS SYSTEMS TESTING - STRONGBACK AND FLAT FLOOR ANDLENT PERFORMANCE TEST. (SPAR/GOVERNMENT REP MANDATORY INSPECTION POINT)

CRITICAL ITEMS LIST

PROJECT: SRMS ASS'Y MOMENCLATURE: <u>ROYAYJONAL HAND CONTROLLER</u> SYSTEM: DEC SUBSYSTEM ASS'Y P/N: SIISSEII7

HEET:

FHEA AEF.	MEV.	NAME OTY A DRAWING REF. DESIGNATION	FAILURE MODE AND CAUSE	FAILURE EFFECF ON END ITEM	HOUR / FUNC. 1/1 HATIONALE FOR ACCEPTANCE CRITICALITY
1460	2	ROTATIONAL HANG CONTROLLER QTY-1 SPAR P/M S11SSE117	MODE: UNCOMMANDED OUTPUT IN ANY ONE AXIS. CAUSE(S): (1) THC DEMODULATOR TRANSISTOR COLLECTOR FAILS OPEN. (2) THC DEMODULATOR TRANSISTOR O-C JUNCTION FAILS SHORTED. (3) RETURN SPRING FRACTURES.	CAUSE (1) ONE AXIS HAS PERHAMENT RATE CONTAND OF 2/3 OF MAX. ARM MAY TAKE UNEXPECTED TRAJECTORY. CAUSE (2) SARE AS ABOVE RATE COMMAND OF 1/3 CI DAX. CAUSE (3) ONE AXIS HAS PERHAMENT RATE COMMAND AT LAST POSITION AND FAKE UNIXPECTED TRAJECTORY. WORST CASE UNEXPECTED MOTION. 6 JOINT RUMANNAY, UNANNUMCIATED. CREW ACTION REQ. REDUNDANT PATHS REHAMING	THERE HAVE BEEN NO FAILURES ASSOCIATED WITH THIS FAILURE MODE ON THE SARS PRICEARM. MO EEE PARTS FAILURES HAVE OCCURRED SUBSEQUENT TO ASSEMBLY OF PARTS. DURING INITIAL ENI TESTING, THE RHC WAS FOUND TO BE SUSCEPTIBLE TO RADIATED EMISSIONS RESULTING IN UNCOMMANDED OUTPUTS IN EACH ARIS. THE PROBLEM WAS RESOLVED BY REDESIGN OF THE ROCKWELL SUPPLIED INTERCONNECT CABLE BTHERE NAKE AND THE DAC PAREL. THIS CABLE, PYSHAYP) TO PAPICS) HAS A DOUBLE SHIELD SYSTEM, WITH 160 DEGREE SHIELD CONTACT AT EACH COMMECTOR.

PREPARED BT: WHE	SUPERCEDING DATE: 06 OCT 87	APPROVED BY:	DATE:

PROJECT: SRMS
ASS'Y NORENCLATURE: ROTATIONAL HAND CONTROLECT

SYSTEM: DEC SUBSYSTEM ASS'Y P/N: STISSETTY

SHEET: _____7 HOUR / FUNC. PAILURE EFFECT FAILURE MODE NAME OTY A RATIONALE FOR ACCEPTANCE AND DRAWING ALF. ACF. REV. CRITICALITY END ITEM DESIGNATION CAUSE CAUSE (1) ONE AXIS HAS OPERATIONAL EFFECTS MODE: ROTATIONAL 2 -1460 UNCOMMANDED HAND PERMANENT RATE OUTPUT IN CONTROLLER ARM DOES NOT RESPOND PROPERLY TO COMMANDS OR DRIVES WITHOUT COMMAND OF 7/3 AMY OTY-I COMMAND. WHEN THE COMMAND IS REMOVED, THE ARM CONTINUES TO OF MAX, ARM MAY SPAR P/N ONE AXIS. DRIVE. TAKE UNEXPECTED 51155E117 TRAJECTORY. CAUSE(S): CREW ACTION (1) RHC DEMODULATOR CAUSE (2) SAME AS ABOVE MATE COMMAND OF TRANSISTOR APPLY BRAKES. COLLECTOR I/) OF MAX. FAILS OPEN. CREW TRAINING CAUSE (3) ONE AXIS HAS (2) RHC **DEMOBULATOR** PERMANENT THE CREW MILL OF TRAINED TO ALWAYS OBSERVE WHETHER THE ARM IS RATE COMMAND ROTELEMANT RESPONDING PROPERLY TO COMMANDS. IF IT ISM'T, APPLY BRAKES. AT LAST B-E JUNCTION POSITION FAILS ARM MAY TAKE SHORTED. MISSION CONSTRAINT UNCXPECTED TRAJECTORY. RETURN OPERATE UNDER VERNIER RATES WITHIN 10 FT OF STRUCTURE. THE SPAING OPERATOR MUST BE ABLE TO DETECT THAT THE ARM IS RESPONDING MORST CASE FRACTURES. PROPERLY TO COMMANDS WIR WINDOW AND/OR CCTV VIEWS DURING ALL ARM OPERATIONS. UNEXPECTED MOTION. 6 JOINT SCHEEN FAILURES RUNAWAY. UNANHUNCIATED. CREW ACTION REQ. OMRSD OFFLINE REDUNDANT PATHS REMAINING WITH THE RHC IN THE MULL POSTION N/A VERIFY VOLTAGES AT RHE OUTPUT IN ALL ANES ORRSD OHLINE INSTALLATION NONE OMRSD ONLINE TURNAROUND WITH THE RHC IN THE WULL POSTION VERIFY BIT COUNT IN ALL AKES

SUPERCEDING DATE: 06 OCT 47 PREPARED BY: MY HG _____

APPROVED BY:

RMS/D&C - 364